

## General Description

The DME 502 is a standalone multi-shot fast gated dual channel camera engine with a resolution of 320x240 pixel (QVGA). It is a highly integrated camera system with a wide field of view (FOV). The operating range is up to 10m on white objects. The camera system is a combination of a epc502 sensor board including a lens system, an LED illumination board and a BeagleBone Black host controller board. Even for mobile devices, only a few additional components are needed to integrate this camera, e.g. in a housing.

The host controller operates the epc502 in all available operation modes and reads the pixel values over the TCMI communication. The controller reads the imager data and delivers the results to an external computer via its integrated API. It is also possible to operate the DME 502 as a standalone sensor system. In this case, application software can be downloaded and run on the BeagleBone Black board also by using the full software framework like the operating system and the API kernel.

129 fps full pixel-field dual channel images are delivered by the epc502 camera chip in maximal configuration. By using the advanced operation modes, this can be boosted up to more than 1'000 images per second! The high degree of integration lays base for straight-forward system integration with minimal part count. The extremely high sensitivity of the optical front end allows to operate with a low power illumination subsystem which reduces the power consumption of the overall system significantly.

The camera comes with a fully documented SDK based on open-source SW and HW.

## Features

- 320 x 240 pixel (QVGA)
- Single (Count 1 image only) or dual channel mode (Count 1 image and Count 2 image)
- Single shot or multi shot
- Free programmable acquisition timing per shot
- Minimum delay time and minimum count window of 12.5ns
- Multi-shot repetition rate down to 62.5ns
- Wide field of view H94° x V69°
- Low power consumption
- Robust and stable
- High speed USB or ETHERNET interface
- Linux server with API kernel

## Applications

- Fluorescence life time imaging (FLIM)
- Nanosecond resolution imaging
- Time-resolved imaging  
e.g. fluorescence, phosphorescence, luminescence
- Time domain based 3D TOF imaging (LIDAR)
- Laser gated imaging (LGI), burst illuminated imaging (BIL)



Figure 1: DME 502

# 1. Precaution and Safety



**Eye safety: Do not look directly into the camera under operation. Depending on the mode of operation, the camera device emits highly concentrated non-visible infrared light. It can be hazardous to the human eye. The use of these devices has to follow the safety precautions given in IEC 60825-1 and IEC62471.**



The DME 502 camera module is a bare electronic device without a housing around. Therefore, handle it with the necessary ESD precaution.



Over-voltage: Use only power supplies which corresponds to the datasheet DME 502 to avoid damage of the DME 502 or cause danger for humans.



Cable-tripping: Place the DME 502 with a tripod on a flat solid ground or fix it correctly on a solid support. Place cables carefully. Falling devices can be damaged or harm persons.



For proper operation of the camera, upload the correct firmware with the evaluation kit to the camera according the instructions given in the quick guide. Do this when you are changing the camera module.



This camera comes with high quality lens. Do not touch, twist or turn it. Otherwise loss of performance occurs.



EMC compatibility: The DME 502 is designed on module level. It is not an EMC certified device. It is users responsibility to operate it in compliance with the EMC regulations.



The DME 502 is designed on module level. It is NOT a CE, UL, CSA certified device. It is the users responsibility to operate it in compliance with the relevant regulations.



The DME 502 and its software may only be used in accordance of the datasheet DME 502



This devices may not be used in safety applications, explosive atmospheres or in radioactive environment.



Limited warranty - Loss of warranty

The DME 502 should only be installed and used by authorized people. All instructions in this datasheet and in the related documents shall be followed and fully complied with. In addition, the installer and user is required to comply with all local laws and regulations. Should any of these instructions not be carefully followed, seriously injury may occur. The installer and user is fully responsible for the safe use and operation of the system. It is the sole responsibility of the installer and the user to ensure that this product is used according to all applicable codes and standards in order to ensure safe operation of the whole application. Any alteration to the devices by the buyer, installer or user may result in unsafe operating conditions. ESPROS Photonics AG is not responsible for any liability or warranty claim which results from such manipulation or disregarding of given operating instructions.

## UPDATES

**ESPROS Photonics is constantly striving to provide comprehensive and correct product information. Therefore, please check our website regularly for updated versions of datasheets and documentations: [www.espros.com](http://www.espros.com)**



Download the actual Datasheet epc502 : [www.espros.com](http://www.espros.com) → Downloads → Datasheets → Chips.



Download the actual Datasheet DME 502: [www.espros.com](http://www.espros.com) → Downloads → Datasheets → Camera\_and\_Modules



Download the current GUI software (client) and the current BeagleBoneBlack software (server).  
Questions: Send an email with your request to your local sales office or to [info@espros.com](mailto:info@espros.com).



Update the DME 502 (BeagleBone board): Go to the folder "ESPROS\_TOF-imager\_Evaluation\_Kit\_Software\_vX.X.X". Read the Readme-file and follow the instructions accordingly.

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## 2. The DME 502 camera module

### 2.1. System overview

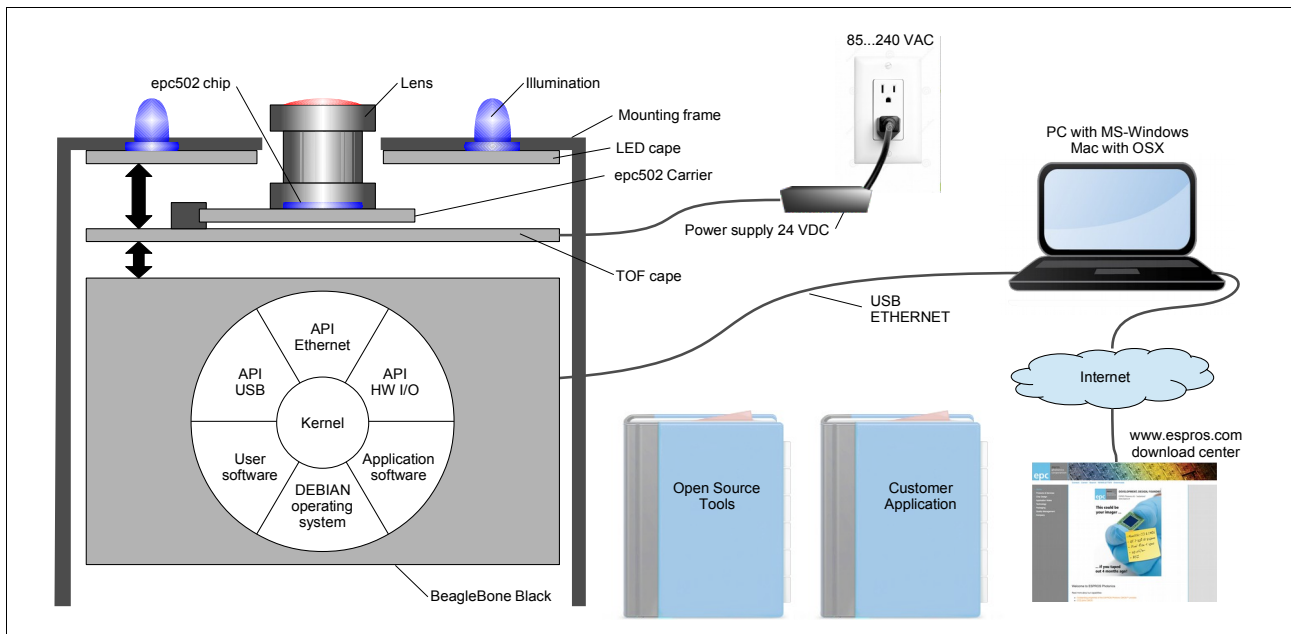


Figure 2: System overview

The DME 502 is a general purpose camera module based on the epc502 chip:

- The camera is based on a BeagleBone Black (BBB) Linux computer board.
- The TOF cape board communicates with the BBB and carries the epc502 Card Edge Connector Carrier board with the epc502 camera chip and the lens with the lens holder. It carries also the single wire power supply for the whole camera system.
- The camera's active illumination is done by 8 power LEDs on the LED cape which is driven by the TOF cape. The LED cape's metal frame offers two camera mount 1/4" - 20UNC.
- The application software runs on the DEBIAN GNU/Linux operating system. The kernel manages the camera. Data for further processing is available on APIs (application programming interface) for USB, Ethernet interfaces or hardware I/O. It opens the world for using open source tools or creating own customer applications.

## 2.2. Scope of Delivery

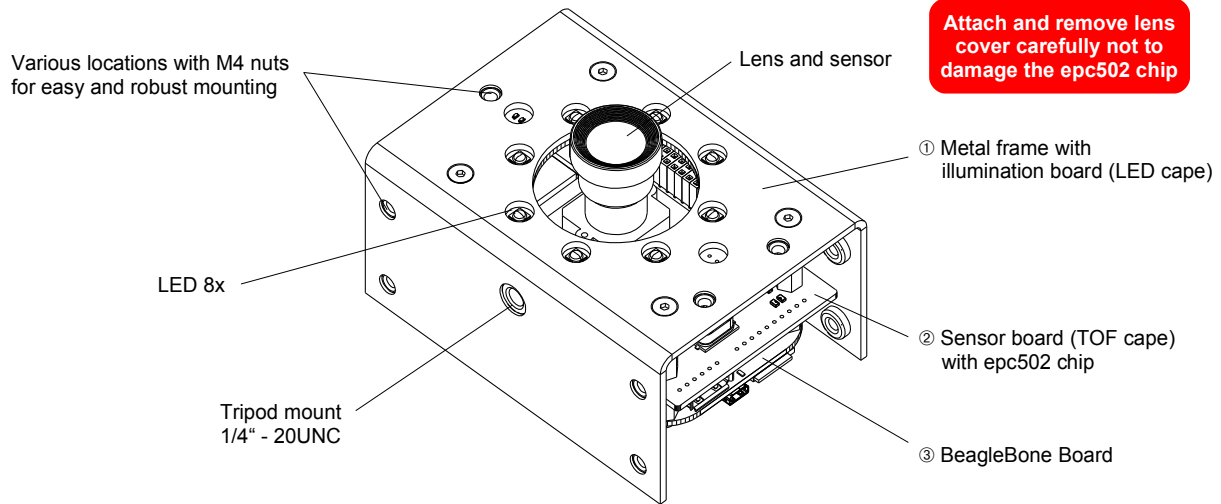


Figure 3: DME 502 overview

### 2.2.1. Bill of Material

No.	Designation	Remarks
①	Metal frame with camera/tripod mount 1/4" - 20UNC	Use only the 1/4" - 20UNC or the M4 tread inserts for mounting the camera
	LED cape: Illumination board	on Metal frame
②	TOF cape: Sensor board	on LED cape
	epc502-CSP68 chip (P/N P100 348) assembled on card edge connector carrier (P/N P100 350)	on TOF cape
	Optical bandpass filter e.g. infrared filter 860nm	included in lens holder (P/N P100 410)
	Lens holder, M12-Mount with 860nm filter (P/N P100 410)	on epc502 card edge connector carrier board. Filter specifications: see Datasheet epc-bp-860.
	Lens for DME 502 (P/N P100 295): - FOV: H94°, V69° - Lens with non-linear distortion - optimized for NIR - EFL 4.1mm (center) - F2.0 - 1/2" - M12 mount	on lens holder, including lens cover  other lens types upon request
③	BeagleBone Black board	Host controller

### 2.2.2. Documentation

Designation	Remarks
Datasheet DME 502	available at <a href="http://www.espros.com">www.espros.com</a> / Downloads
Datasheet epc502	available at <a href="http://www.espros.com">www.espros.com</a> / Downloads
Application and configuration software	use the epc502 Evaluation Kit for accessing licensed corresponding tools and software development kit (SDK).

Table 1: Bill of material of the delivery

### 3. Ordering Information

Part Number	Part Name	Remark	RoHS compliance
P100 368	DME 502-94°/10m	completely assembled, tested and calibrated	Yes

#### Accessories:

Part Number	Part Name	Remark	RoHS compliance
P100 350	epc502-000 Card Edge Connector Carrier	epc502 on chip carrier without optical filter	Yes
P100 295	Lens FOV 122°, 1/2", M12	Lens for DME 502: - FOV: H94°, V69° - Lens with non-linear distortion - optimized for NIR - EFL 4.1mm (center) - F2.0 - 1/2" - M12 mount	
P100 410	Lens holder, M12-Mount with 860nm filter		
	Optical bandpass filter	included in lens holder	

Table 2: Ordering Information

Support and technical contact: [info@espros.com](mailto:info@espros.com)

## 4. Technical Data

### 4.1. Recommended operating conditions

( $T_A = 25^\circ\text{C}$ ,  $V_{\text{SUPPLY}} = 24\text{V}$ , object reflectivity 90%, unless otherwise stated)

Parameter	Description	Min.	Typ.	Max.	Units	Comments
$V_{\text{SUPPLY}}$	Supply voltage	21.6	24	26.4	VDC	
$V_{\text{PP}}$	Ripple on the supply voltage $V_{\text{SUPPLY}}$			0.25	$V_{\text{PP}}$	Peak value must not be below min. and not above max. supply voltage
$I_{\text{SUPPLY}}$	Supply current		0.10		A	after power up
	Imaging, actively illuminated		0.25		A	25 fps, $t_{\text{INT}} = 1\text{ ms}$
	Image resolution	320 x 240			Pixel	
FOV	Field of view	H94 x V69			°	with lens P/N P100 295
$\lambda_{\text{LED}}$	Operating wavelength	850			nm	Illumination LEDs
$A_{\text{PIXEL}}$	Photosensitive area		20 x 20		$\mu\text{m}$	1 pixel
$A_{\text{SENSOR}}$	Photosensitive area		6.4 x 4.8		mm	320 x 240 pixel
CG	Conversion gain		0.01026		LSB/e-	
$H_v$	Optical sensitivity		57'508		$\frac{\text{LSB}}{\text{Lux/sec}}$	@ $\lambda = 630\text{nm}$
S	Grayscale sensitivity (conversion rate)		61.5		$\frac{\text{nW/cm}^2}{\text{LSB}}$	@ $\lambda = 850\text{nm}$ , Integration time = 103 $\mu\text{sec}$ .
$t_{\text{INTB\_MGA, MGB}}$	Basic integration time for MGA, MGB (Shutter time)	12.5ns		819.2 $\mu\text{s}$		Total integration time = basic integration time x number of cycle repetitions
$t_{\text{FLASHB}}$	Basic flash time	12.5ns		819.2 $\mu\text{s}$		Total illumination time = basic flash time x number of cycle repetitions
	Delay times START-FLASH, START-MGA, MGA-MGB, MGB-END.	12.5ns		819.2 $\mu\text{s}$		Refer to Figure 5
	Cycle time	62.5ns				
$t_{\text{REP}}$	Number of cycle repetitions	1		65'535		
d	Operating range	0.00		10.0	m	Measured with an object that has a size at least the size of the pixel ( $d_{\text{PIX-EL}}$ ). It is depending on the integration time $t_{\text{INT}}$ and the object reflectivity.
Out	Grayscale data	12			Bit	
A	Amplitude (Measurement output)	0		2'047	LSB	Dynamic range for grayscale measurement
	Data interface	USB 2.0 full speed or Ethernet				
$T_{\text{PWR\_UP}}$	Power up time		20		s	
$T_A$	Operating temperature range	0		60	°C	Ambient

Table 3: Operating conditions

### 4.2. Optical Power Data

Parameter	Description	Min.	Typ.	Max.	Units	Comments
$E_{\text{e PEAK}}$	Peak illumination irradiance			372	$\text{W/m}^2$	in 200mm distance to the front surface of the DME 502

Table 4: Optical power data

The analysis of the photo-biological hazards show that the DME 502 emits radiation levels below the safety limits described in EN 62471. The calculated exposure level is below the limit for any exposure time at a distance of 200 mm or more. Therefore, the DME 502 can be assumed to be safe to the eye and skin in terms of the standard and would belong to the open group (RG0).

Refer for details to the report 'DME\_660\_Photobiological\_Safety\_Analysis.pdf' which is applicable also for the DME 500. It can be downloaded from the ESPROS website.

### 4.3. Operating modes

Refer to the Datasheet epc502 and the epc502 Evaluation Kit for detailed description of the operating modes epc502.

The screenshot shows the epc502 software interface with the following sections:

- View:** Includes 'Picture' and 'Stop' buttons, and checkboxes for 'Show pixel information' and 'Show temperature'.
- FLIM:** A waveform graph showing 'flash' (red), 'mga' (blue), and 'mgb' (green) pulses. Below the graph are input fields for 'Flash', 'Mga', 'Mgb', 'Repetition time', and 'Repetitions'.
- ROI:** Input fields for 'Lower left corner' (x=4, y=6) and 'Upper right corner' (x=323, y=245), with a 'Default ROI' button.
- BINNING AND REDUCTION:** Checkboxes for 'Vertical binning' and 'Horizontal binning', and a 'Row reduction' dropdown set to 'Full'.
- TRANSFORMATION:** Checkboxes for 'Horizontal flip' and 'Vertical flip'.

Single shot picture or movie  
 Display pixel detail data of the pixel pointed by the cursor.

Red: Flash pulse delay and flash pulse length  
 Blue: MGA delay and basic integration time MGA  
 Green: MGB delay and basic integration time MGB  
 Black: Repetition time delay

Set flash pulse delay and flash pulse length  
 Set MGA delay and integration time MGA  
 Set MGB delay and integration time MGB  
 Set repetition time delay  
 Set number of cycle repetitions  
 Total integration time = basic integration time x number of cycle repetitions

Image reduction by setting a region of interest:  
 Coordinates of displayed pixels

Emulation of epc503 device

Combines 2 vertically adjacent pixel into one (120 rows only)  
 Combines 2 horizontally adjacent pixel into one (160 columns only)  
 Shows all, 1/2, 1/4, or 1/8 of the rows

Flipping of displayed image

Figure 4: Overview of the operating modes epc502 Evaluation Kit



### 4.3.1. Measurement Timing

e.g. double shot measurement for FLIM application)

The epc502 provides a 2 shot measurement with a programmable LED flash pulse (FLIM-flash) and two programmable detection windows (Count 1 and Count 2). It allows for example to do FLIM measurements (Fluorescent Life Time Imaging) whereas the decay of the fluorescence is estimated by stimulating a sample with light and measuring by counting windows (shots) the emitted light power. Before readout, this so called FLIM cycle is repeated n times to increasing the signal amplitude.

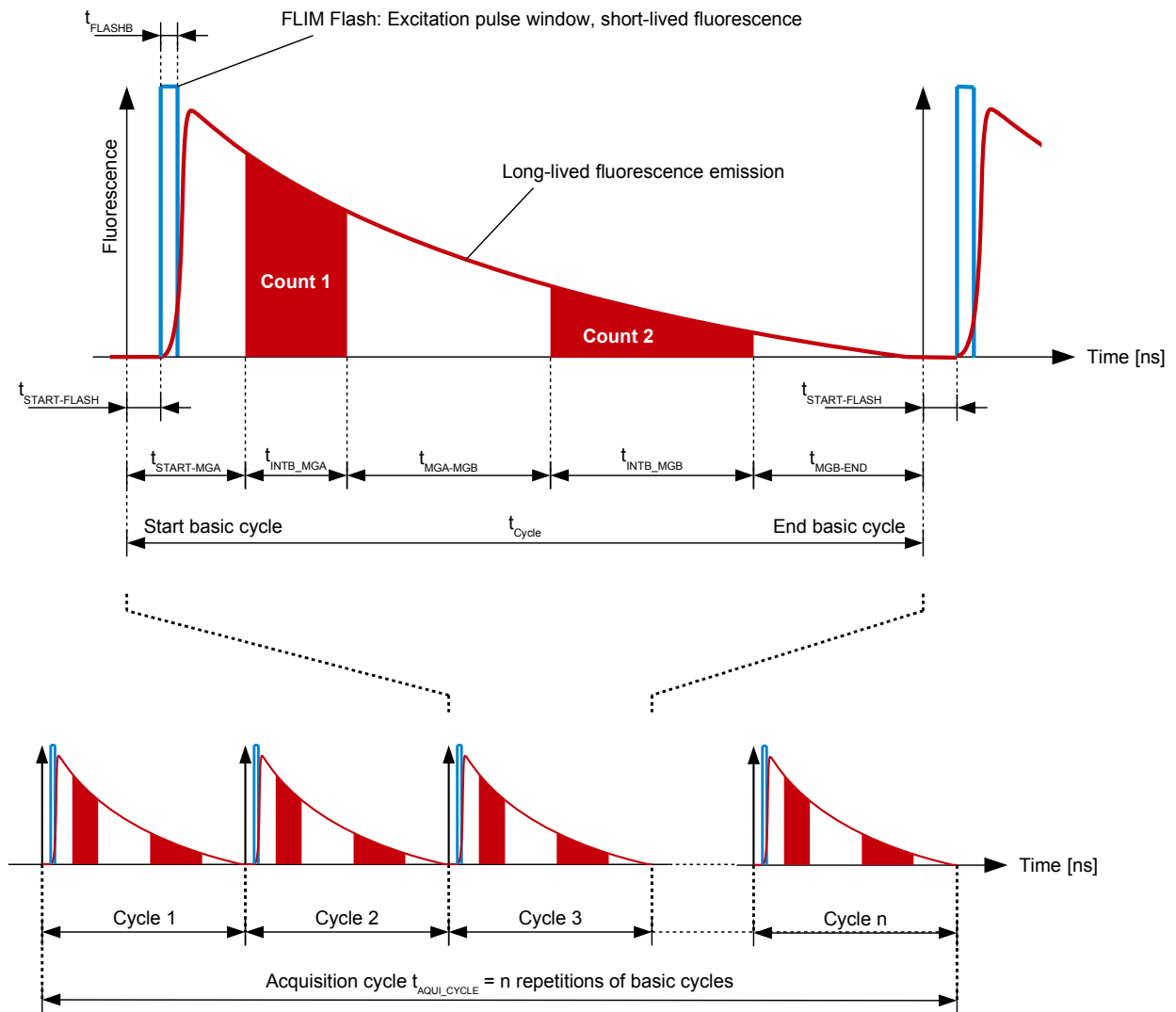


Figure 5: Double shot measurement with stimulation

Figure 6 shows the overall measurement timing diagram. After each acquisition, the two images containing the pixel data has to be read out from the epc502 imager.

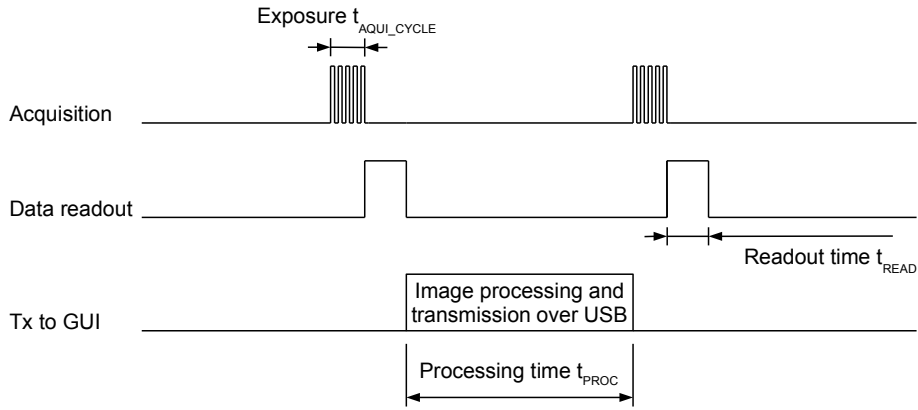


Figure 6: DME 502 measurement timing (standard API)

**4.4. Absolute Maximum Ratings**

Parameter	Conditions
ESD rating	Not classified. Handle it with the necessary ESD precaution.
Storage temperature range (T <sub>s</sub> )	-40°C to +85°C
Relative humidity	15 ... 95%, non-condensing

Table 5: Absolute maximum ratings

## 5. Interfaces

### 5.1. Connectors

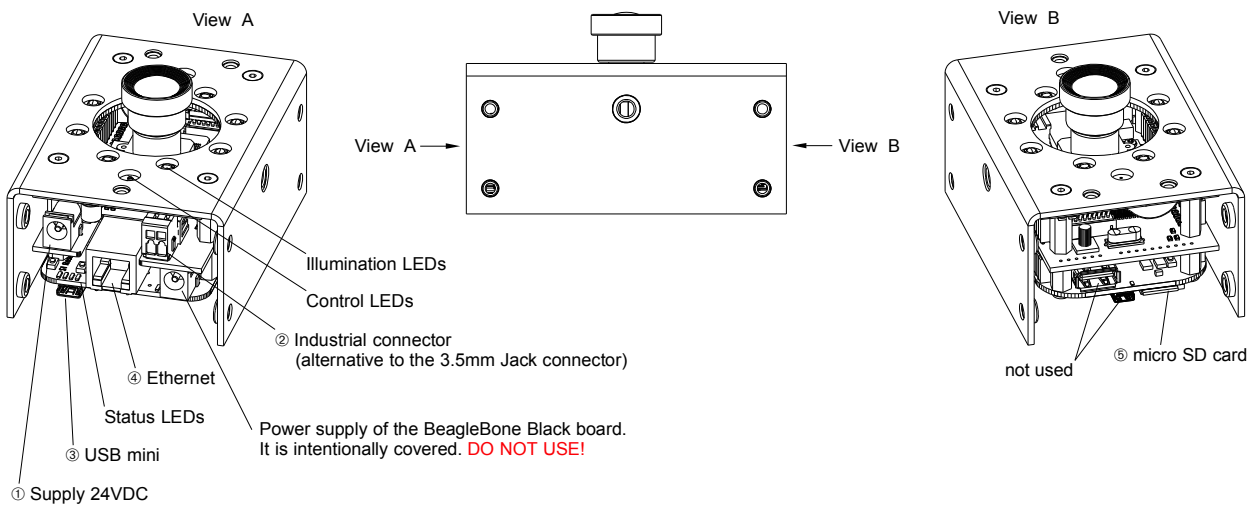


Figure 7: Connectors, status and control LEDs



No.	Connector	Plug	Remarks
①	Supply 24VDC / 2.5A	Power jack 5.0/2.1mm	for supply from power adapter 24VDC / 2.5A
②	Industrial supply	Power jack WAGO 3.5mm	for supply by industrial connection 24VDC / 2.5A
③	USB micro	Micro USB-B	 <b>NEVER CONNECT THE USB CABLE AS LONG POWER IS NOT TURNED ON COMPUTER AND/OR THE CAMERA CAN BE DAMAGED!</b> 
④	ETHERNET	RJ45	
⑤	Micro SD card		

Table 6: Connector list

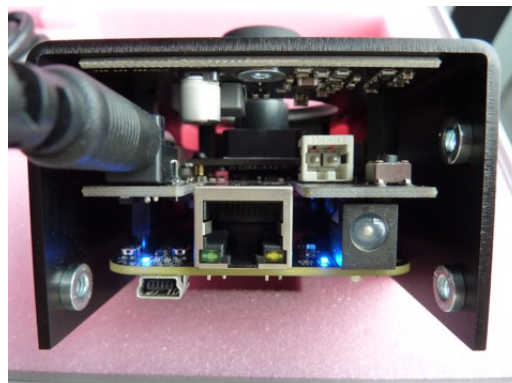


Figure 8: View to the connector side (USB and ETHERNET not connected)

## 5.2. Indicators and reset button

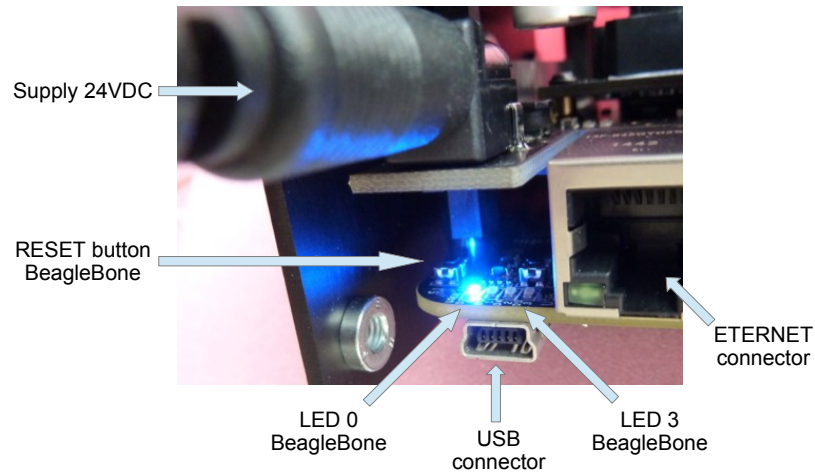


Figure 9: Status LEDs and RESET button

### 5.2.1. Status LEDs

Status	LED 0	LED 1	LED 2	LED 3	Remarks
Start-up DME 502 or BeagleBone: The blue status LEDs start flashing	☒	☒	☒	☒	After power up or RESET. Startup procedure of the board operating system. For details refer to the BeagleBone manual
<b>After around 20s: Boot epc502 chip</b>					
Trying to boot the epc502 chip	☒	☒	☒	■	Wait until LED 0 only (most left) is flashing only. LEDs 1 to 3 shall be off.
READY for handling requests	☒	☐	☐	☐	Server successfully started on DME 502. Start communicating with the BeagleBone Black server by using either Ethernet or USB.
<b>Regular operation:</b>					
BUSY: Handles request of single command or video	☒	☐	☐	■	
READY again	☒	☐	☐	☐	
<b>Error message:</b>					
Caught signal (Error), application closed	☒	■	■	■	Error detected by API. Reset the BeagleBone.

Table 7: Blue status LEDs on BeagleBone, refer to Figure 9

Notes:

- ☐ LED off
- ☒ LED flashing
- LED on

### 5.2.2. Monitoring LEDs

Red control LEDs on LED Cape, visible from the frontside; refer to Figure 7:

- D12: On if the LED cape is powered e.g. imaging mode. **Safety advise: Be careful, IR LEDs are active during exposure.**  
Off during modes having not an active illumination e.g. image mode without active illumination.
- D13: On during integration period (exposure) independent of selected mode.

### 5.2.3. Reset button on BeagleBone

Resets the DME 502. Instead of the this button, the terminal command, as described in the "Readme" of the GUI source, can be used.

### 5.2.4. Reset button on TOF cape

Do not use. Resets the epc502 chip only. Lost of the synchronization with the BeagleBone board.

## 6. Mechanical Properties

### 6.1. Part list

No.	Part name	Qty.
1	BeagleBone Black Rev. C	1
2	Illumination board: LED cape	1
3	Distance sleeve M3/18mm, hole/hole, PA	4
4	Distance sleeve M3/12mm, bolt/hole, PA	4
5	Screw - cylinder head, cross recess, M3x6	4
6	Metal frame	1
7	Nut self-clinching	2
8	Sunk screw, M3x8	4
9	Lens FOV 122°, 1/2", M12 (P/N P100 295)	1
10	Connection Cable	1
11	Lens holder, M12-Mount with 860nm filter	1
12	Sensor board: TOF Cape	1
13	Screw - cross recessed, M1.6x3	2
14	Mounting pillar	2
15	Screw - cross recessed, M2x5	2
16	Female header Dip, 2.54, 180°	1
17	epc502 Card Edge Connector Carrier	1
18	5.0/2.1mm DC Power Jack 24VDC / 2.5A	1
19	Industrial supply female plug	1
20	Industrial supply male connector	1
21	Micro SDHC card 16GB, programmed	1

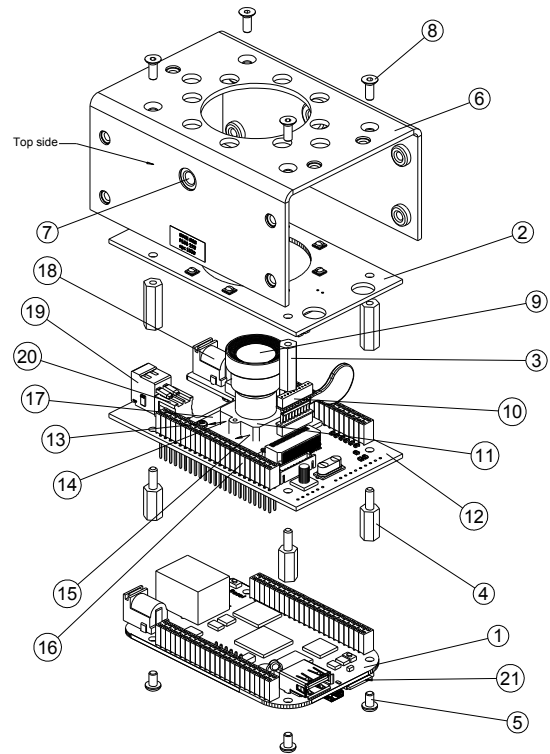


Figure 10: Part list and exploded view

### 6.2. Mechanical / Optical Properties

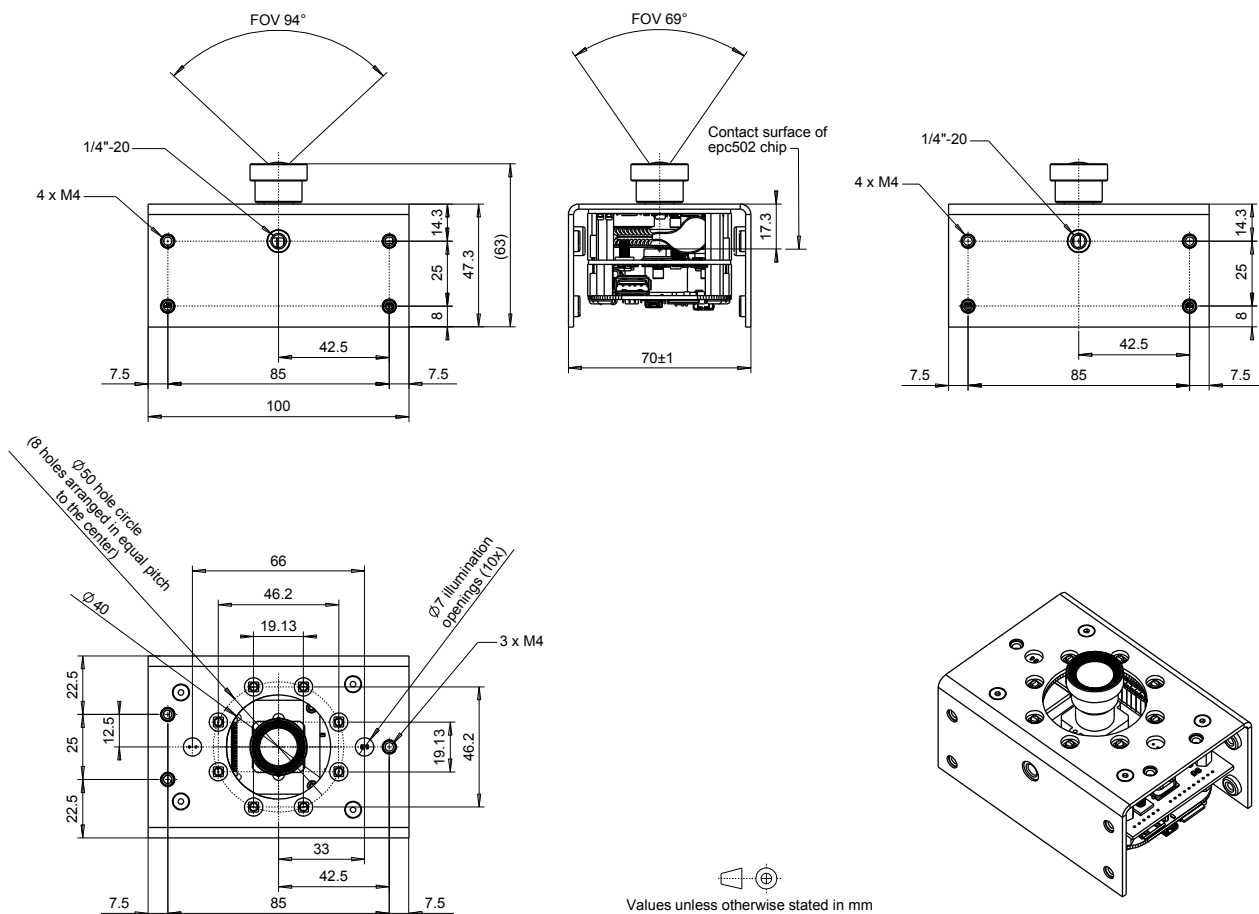


Figure 11: Reference dimensions of the optical axis and illumination

## 7. Electrical Circuits

Note: The DME 502 uses the DME 660 hardware in combination with an epc502 chip instead of an epc660 chip.

### 7.1. epc502 on Card Edge Connector Carrier

#### 7.1.1. Schematics

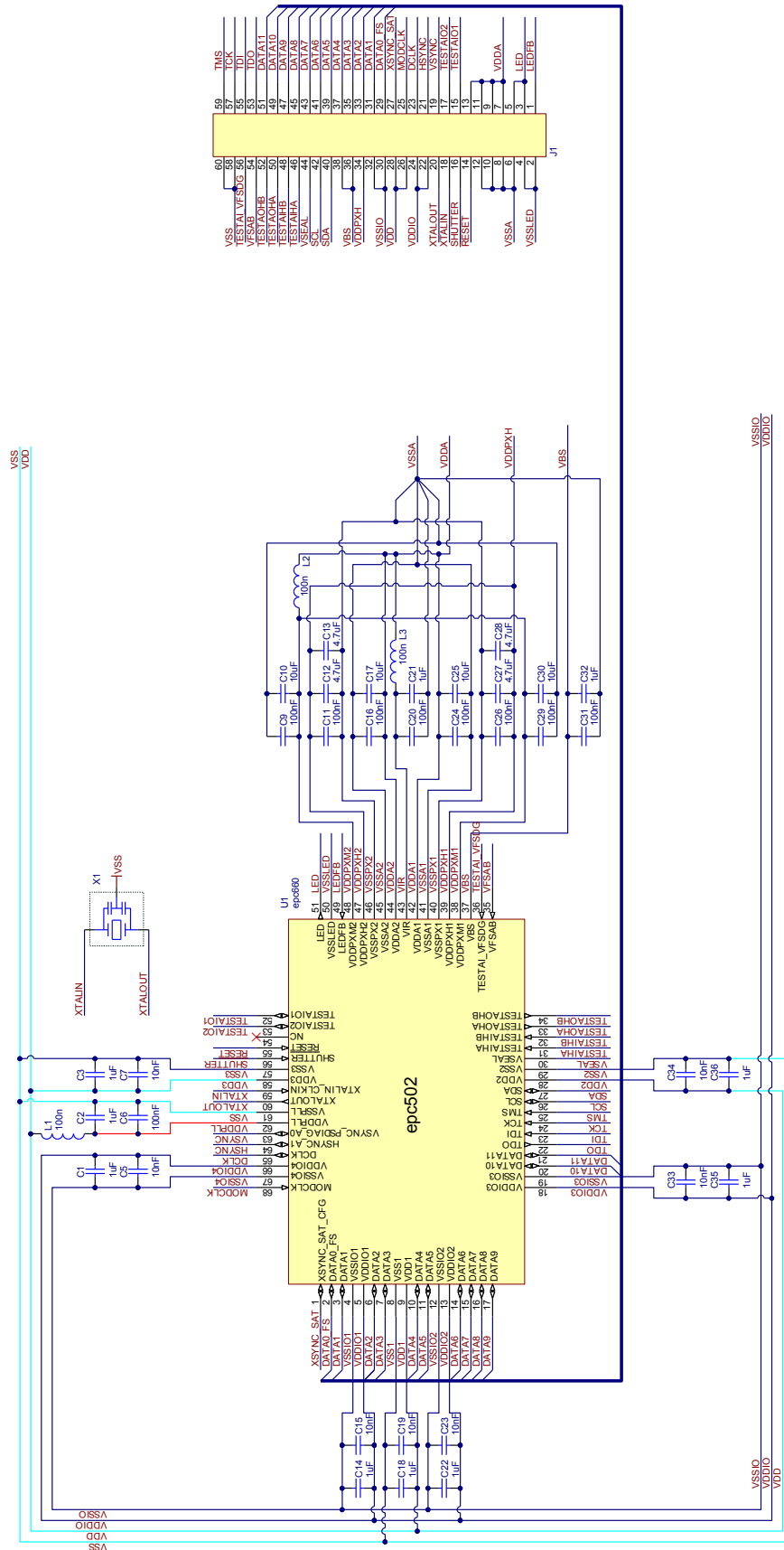


Figure 12: Schematic

7.2. PCB Layout

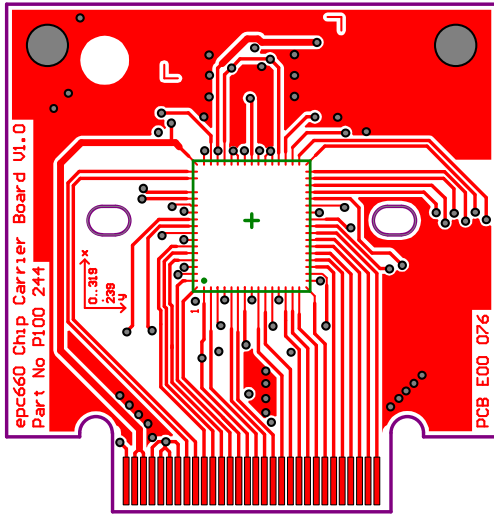


Figure 13: PCB layout top

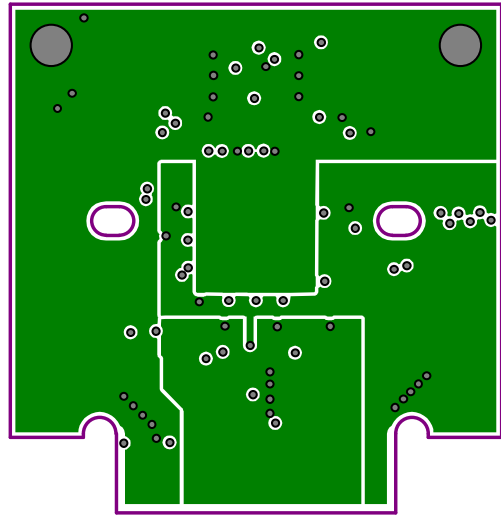


Figure 14: PCB layout top-middle

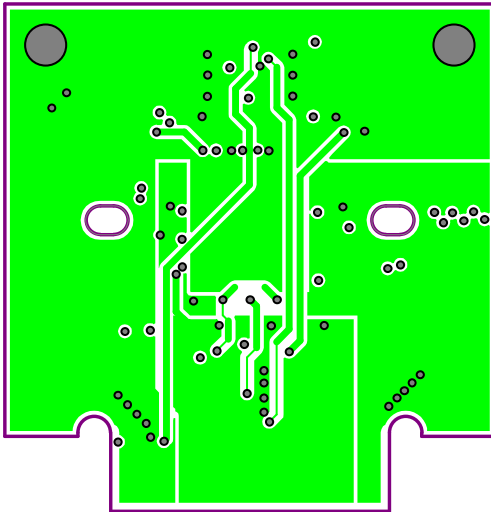


Figure 15: PCB layout bottom-middle

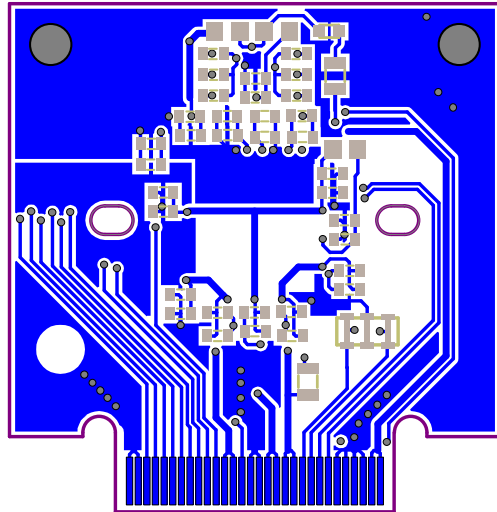


Figure 16: PCB layout bottom

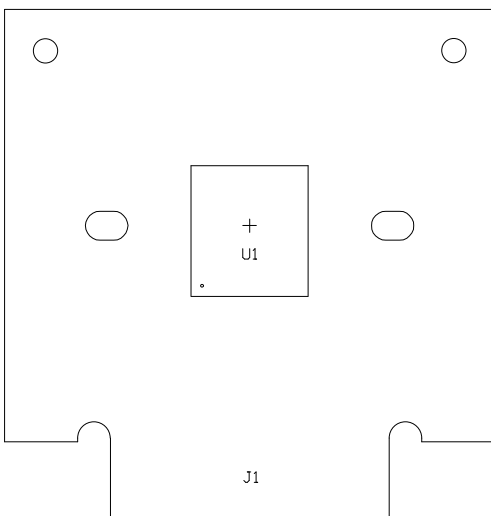


Figure 17: PCB assembly top

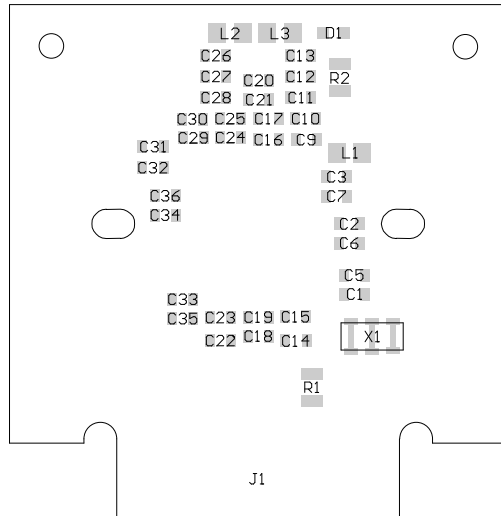


Figure 18: PCB assembly bottom

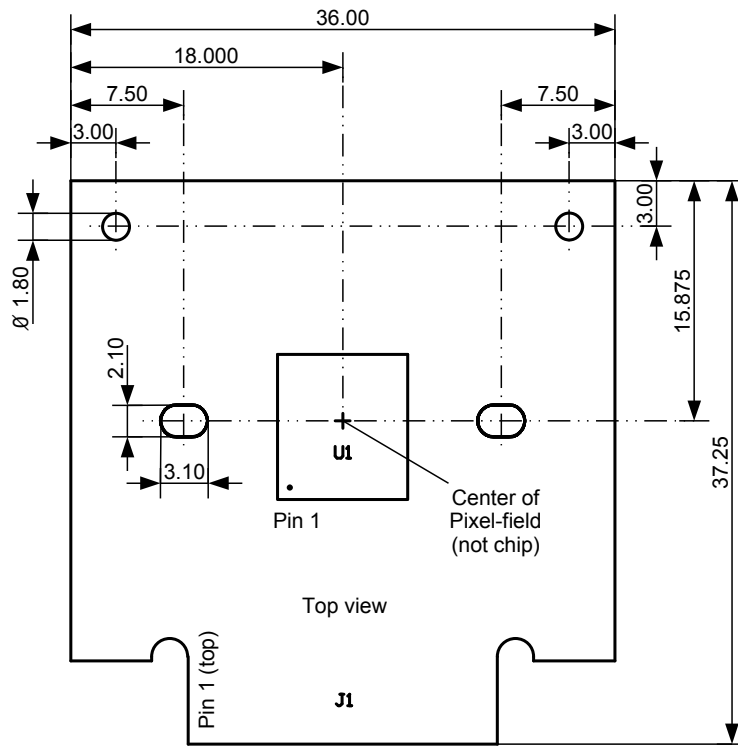


Figure 19: Mechanical dimensions PCB

### 7.3. Pin Table

60	59	TMS
VSS	58	TCK
TESTAI_VFSDG	56	TDI
VFSAB	54	TDO
TESTAOHB	52	DATA11
TESTAOHA	50	DATA10
TESTAIHB	48	DATA9
TESTAIHA	46	DATA8
VSEAL	44	DATA7
SCL	42	DATA6
SDA	40	DATA5
	38	DATA4
VBS	36	DATA3
VDDPXH	34	DATA2
	32	DATA1
VSSIO	30	DATA0_FS
VDD	28	XSYNC SAT
	26	MODCLK
VDDIO	24	DCLK
	22	HSYNC
XTALOUT	20	VSYNC
XTALIN	18	TESTAIO2
SHUTTER	16	TESTAIO1
RESET	14	
	12	
	10	
	8	VDDA
VSSA	6	
	4	LED
VSSLED	2	LEDFB

Figure 20: Pin table



# 8. TOF Cape

## 8.1. Schematics

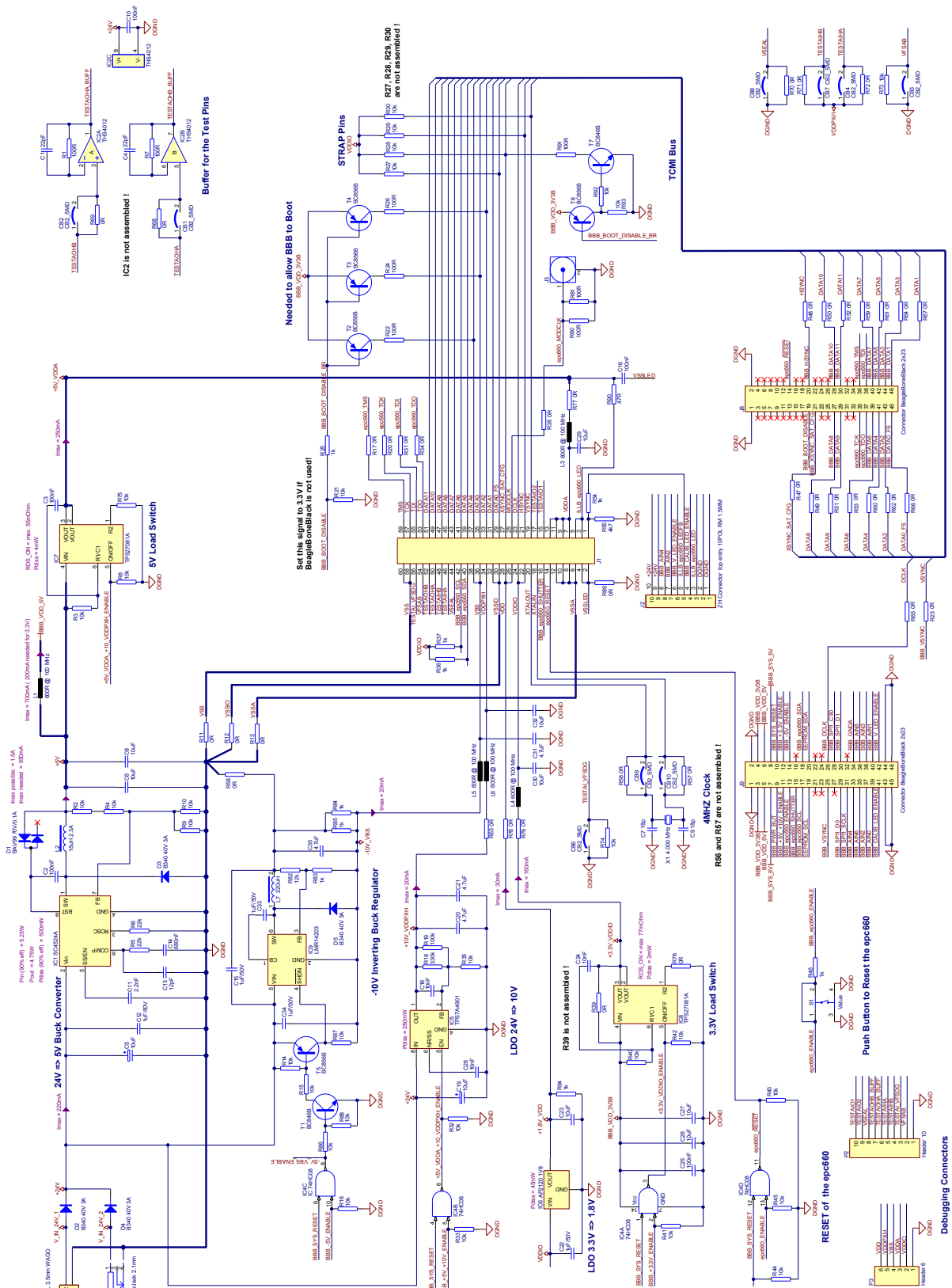


Figure 21: Schematic

## 8.2. PCB Assembly

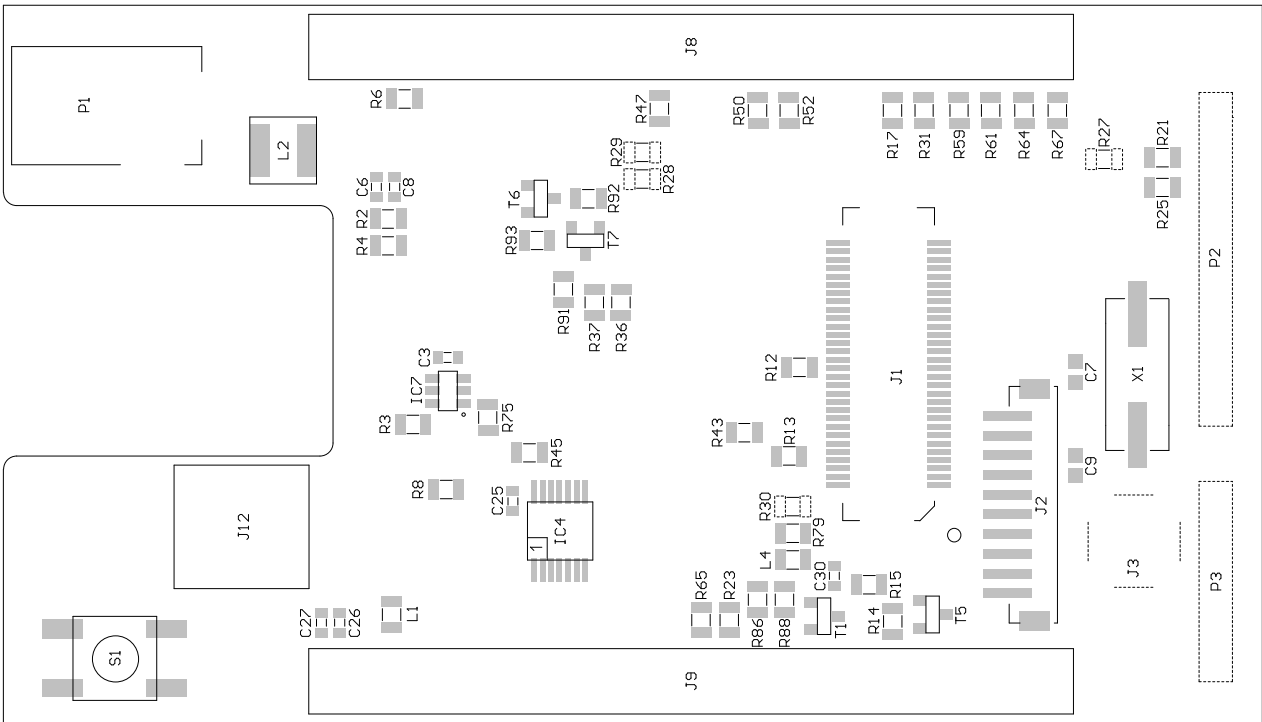


Figure 22: PCB assembly top

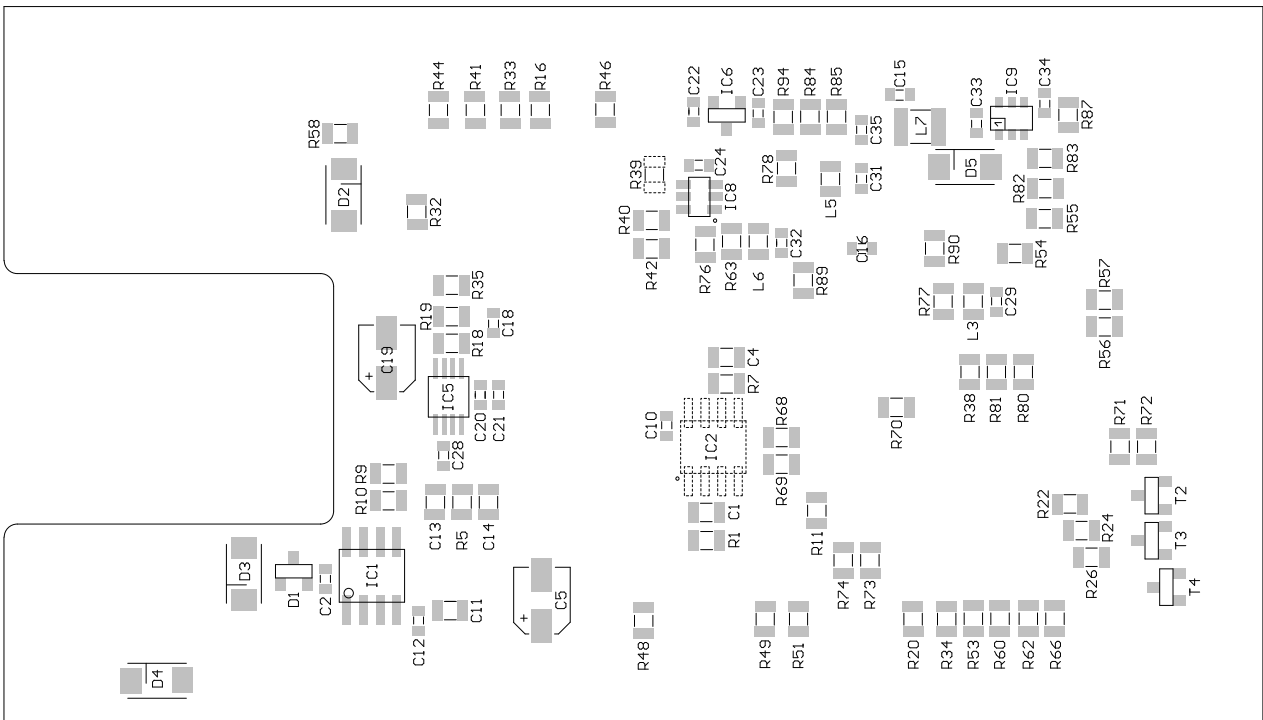


Figure 23: PCB assembly bottom

### 8.3. Pin Table J8 & J9

DGND	<b>1</b>	<b>2</b>	DGND	DGND	<b>1</b>	<b>2</b>	DGND
BBB_VDD_3V3B			BBB_VDD_3V3B				
BBB_VDD_5V			BBB_VDD_5V				
BBB_SYS_5V			BBB_SYS_5V				
BBB_PWR_BUT	<b>9</b>	<b>10</b>	BBB_SYS_RESET		<b>9</b>	<b>10</b>	
BBB_+5V_+10V_ENABLE			BBB_+3.3V_ENABLE				
BBB_epc660_ENABLE			BBB_-5V_ENABLE				epc660_RESETn
BBB_epc660_SHUTTER			---				
BBB_epc660_SCL			BBB_epc660_SDA				
EEPROM_SCL	<b>19</b>	<b>20</b>	EEPROM SDA	BBB_BOOT_DISABLE	<b>19</b>	<b>20</b>	BBB_HSYNC
---			---	BBB_XSYNC_SAT			
---			---				
BBB_VSYNC			BBB_DCLK				
---			BBB_SPI1_CS0	BBB_DATA8			BBB_DATA10
BBB_SPI1_D0	<b>29</b>	<b>30</b>	BBB_SPI1_D1	BBB_DATA9	<b>29</b>	<b>30</b>	BBB_DATA11
BBB_SPI1_SCLK			---				
BBB_AIN4			BBB_GNDA				
BBB_AIN6			BBB_AIN5	epc660_TCK			epc660_TMS
BBB_AIN2			BBB_AIN3	epc660_TDO			epc660_TDI
BBB_AIN0	<b>39</b>	<b>40</b>	BBB_AIN1	BBB_DATA6	<b>39</b>	<b>40</b>	BBB_DATA7
BBB_CALIB_LED_EN			BBB_V_LED_ENABLE	BBB_DATA4			BBB_DATA5
DGND			DGND	BBB_DATA2			BBB_DATA3
DGND			DGND	BBB_DATA0_FS			BBB_DATA1
	<b>J9</b>				<b>J8</b>		

Figure 24: Pin table J8 & J9

# 9. LED Cape

## 9.1. Schematics

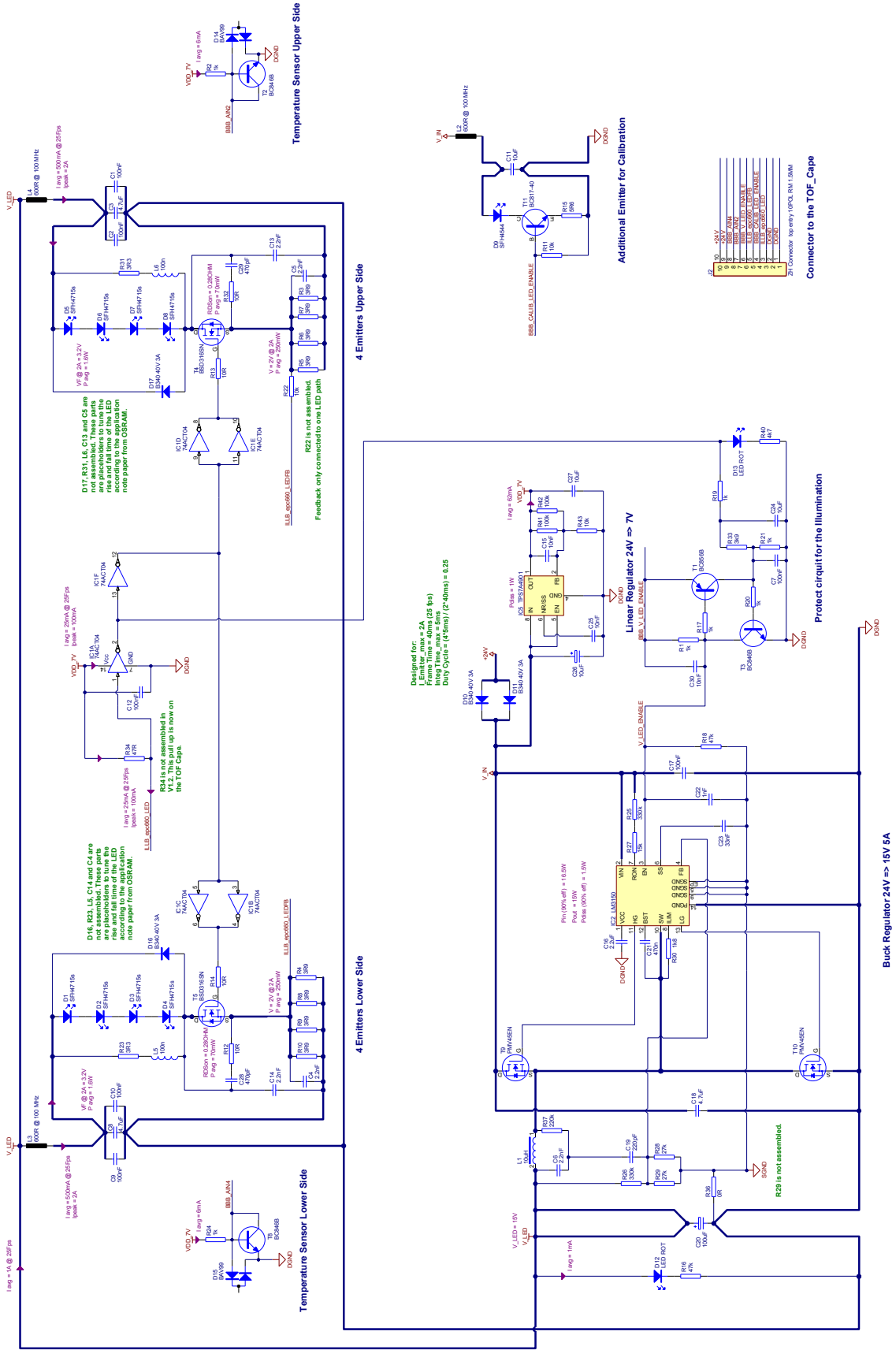


Figure 25: Schematics

## 9.2. PCB Assembly

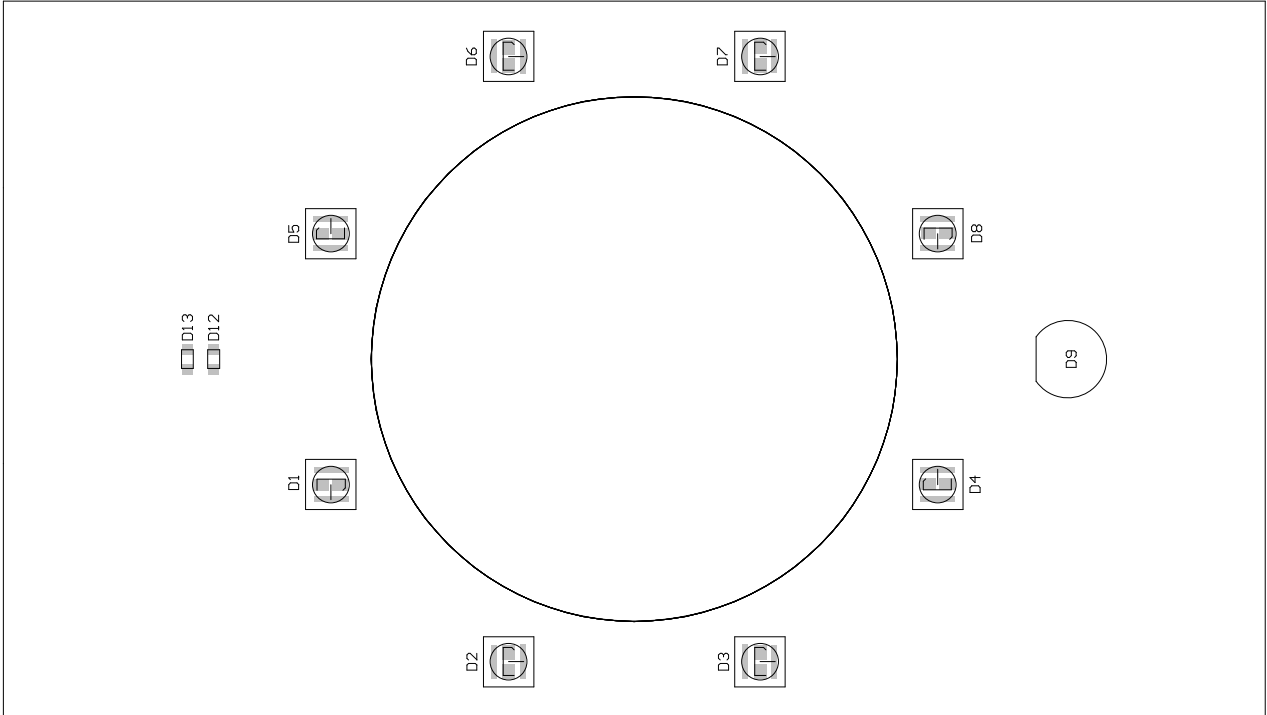


Figure 26: PCB assembly top

- D1..D8: Illumination LEDs  
 D12, D13: Monitoring LEDs (red), refer to chapter 5.2.2, Monitoring LEDs

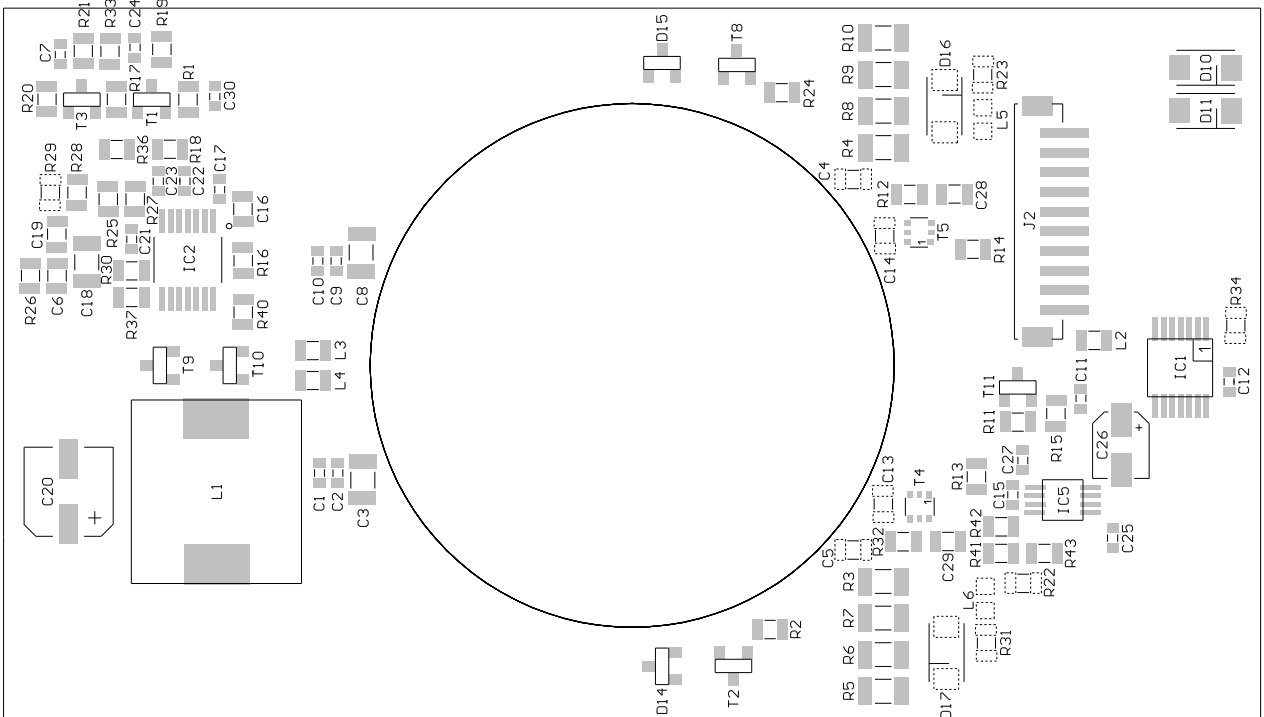


Figure 27: PCB assembly bottom

## 10. BeagleBone Black Board

### 10.1. System Overview

- Processor: AM335x 1GHz ARM® Cortex-A8
- 512MB DDR3 RAM, 4GB 8-bit eMMC on-board flash storage
- 3D graphics accelerator, NEON floating-point accelerator, 2x PRU 32-bit micro controllers
- USB client for power & communications, USB host, Ethernet
- Software Compatibility: Debian, Android, Ubuntu, much more
- Open-source tools for different applications available

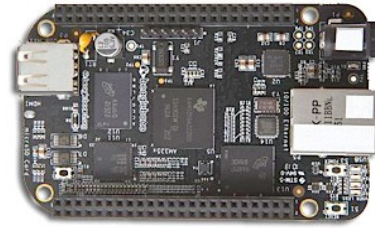


Figure 28: The BeagleBone Black board

### 10.2. Modification on BeagleBone board

The BeagleBone board is modified the following way for working properly in combination with the DME TOF cape.

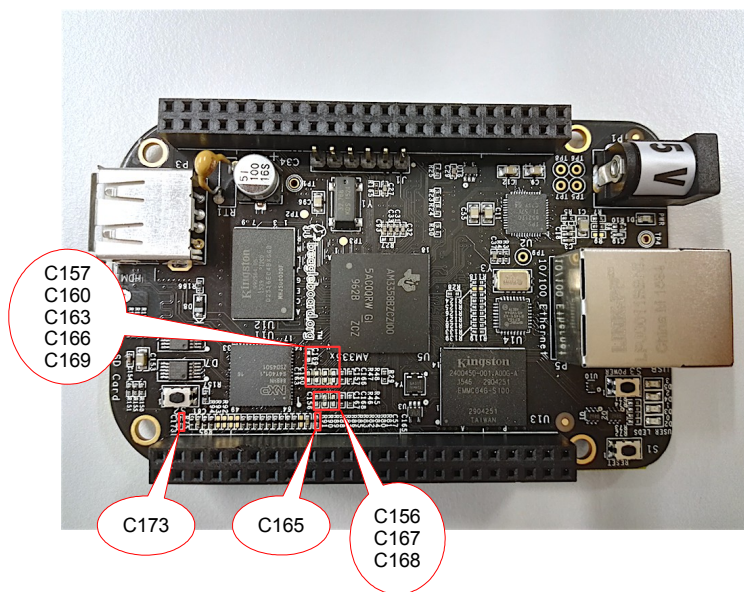


Figure 29: Marked capacitors are removed/disassembled from the Beagle Bone board top side

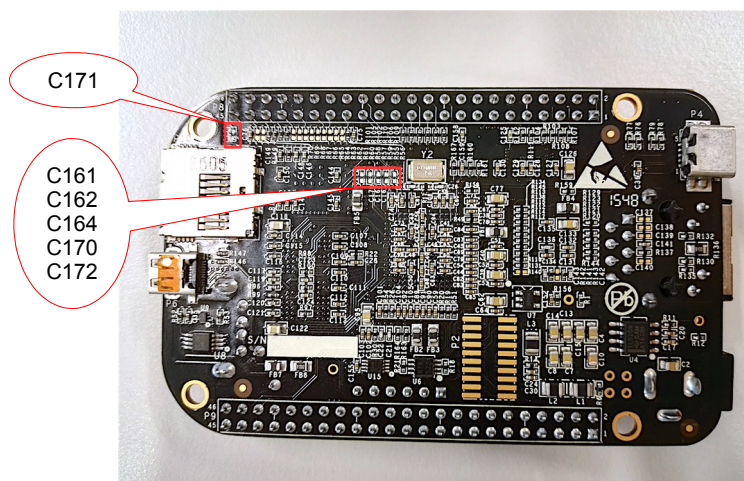


Figure 30: Marked capacitors are removed/disassembled from the Beagle Bone board bottom side

### 10.3. Documentation

Technical description of the BeagleBone Black board can be downloaded from [www.beagleboard.org](http://www.beagleboard.org).

- BeagleBone Hardware Specs and Material, BeagleBone Black wiki
- BeagleBone Black System Reference Manual, BeagleBoard.org, 2014
- BeagleBone Black, Document No. 450-5500-001 (Schematics), BeagleBoard.org, 2014

## 11. Installation and Setup

### 11.1. Mechanical fixation

The DME 502 has various mounting options provided by the metal frame:

- On each long side
  - one tripod mount 1/4" - 20UNC, refer to Figure 3
  - four nut M4
- On top side: three nut M4

Use the options only to attach the DME 502 to a housing, a tripod or something else. Never use the threaded pillars or attach something directly to one of the PCB. You may damage the PCB.

### 11.2. Setup of the DME 502

The DME 502 can be operated by using the GUI software provided with the epc502 Evaluation Kit. The setup is described in the QUICK START GUIDE.




### 11.3. Software Tools

ESPROS Photonics supports the user's development and application by having available various support tools e.g. software development kit (SDK), updates and emulation program downloads for the epc502 chip, application interfaces (API), etc. They are available by contacting ESPROS by email at [info@espros.com](mailto:info@espros.com). The same way, the user can update the DME 502 (BeagleBone board) by using this service.

### 11.4. Exchange of epc 502 Card Edge Connector Carrier



Make sure, all assembly procedures are executed on an ESD-compatible workstation.

- Power off the DME 502 and remove cables
- Remove the BeagleBone board
- Remove the TOF cape
- Remove the locking screws from the epc502 Card Edge Connector Carrier
-  Softly remove the epc502 Card Edge Connector Carrier. The epc502 chip can be destroyed when excessive force is applied.
- Remove lens holder
- Attach the lens holder to the new epc502 Card Edge Connector Carrier
-  Softly insert the new epc502 Card Edge Connector Carrier
- Insert the locking screws for the epc502 Card Edge Connector Carrier
- Install the TOF cape
- Install the BeagleBone board
-  First power on the DME 502
- Connect the USB cable
- Download and install the latest server software according the Readme.txt
- Start the epc502 Evaluation Kit GUI and run a black & white video (start)
- Unlock the fixation of the lens
- Adjust lens focus
- Lock the fixation of the lens
- Calibrate the DME 502 with this new chip carrier

## 12. epc502 Evaluation Kit

There is an evaluation kit available which supports the development of own applications on the DME 502 in terms of the evaluation of the optical performance parameters.

### 12.1. Scope of Delivery



Figure 31: epc502 Evaluation Kit overview

No	Pieces	Designation	Remarks
①	1	Toolbox	
②	1	DME 502-94°/10m	P100 368; with quick release fastener of the tripod
③	1	Power Supply 24V/2.5A	
④	1	Power cord 2 pole EU version and US Adapter	Power plug EU Europlug (CEE7/16, 2 pole) Power plug US Type A (NEMA 1-15, 2 pole)
⑤	1	Cable - USB 2.0, A plug - mini-B plug	Length 2m
⑥	1	Plastic bag with Industrial Supply Connector and the toolbox key	The connector can also be inserted in the DME 502
⑦	1	Camera Tripod	
⑧	1	Toolbox belt	
⑨	1	epc502 Evalkit Quick Start Guide	also available at <a href="http://www.espros.com/Downloads">www.espros.com/Downloads</a>
		Datasheet DME 502	available at <a href="http://www.espros.com/Downloads">www.espros.com/Downloads</a>
		Datasheet epc502	available at <a href="http://www.espros.com/Downloads">www.espros.com/Downloads</a>
		Application and configuration software, SDK	Use the epc502 Evaluation Kit for accessing licensed corresponding tools and software development kit (SDK).

Table 8: Bill of material of the delivery

### 12.2. Ordering Information

Part Number	Part Name	Remarks
P100 366	epc502 Evaluation Kit EU & US	Power plug EU Europlug (CEE7/16, 2 pole) & US adapter

Table 9: Ordering information epc502 Evaluation Kit





Figure 32: DME 502 on tripod



Figure 33: epc502 Evaluation Kit



Figure 34: DME 502 tripod mounting

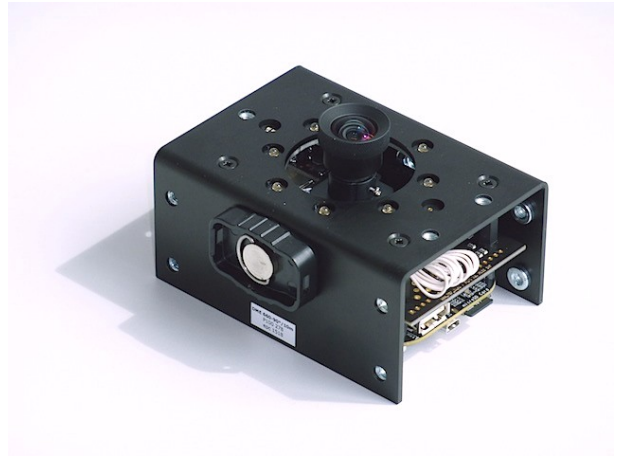


Figure 35: DME 502 with quick release fastener of the tripod



Figure 36: Pictures MGA and MGB

## 13. Maintenance and disposal

### 13.1. Maintenance

The components of the device do not need regular maintenance. A functional check is recommended each time the device is taken into operation:

- Check the mounting position and the detection area of the sensor with respect to the operational conditions. Also check that there is no hazardous situation.
- From time to time, clean the lens with a soft towel and with a little soapy water to remove dust or dirt.

### 13.2. Disposal

Disposal should be done using the most up-to-date recycling technologies for electronic components according to the local regulations and laws. The design and manufacture of the kit's components are done in compliance with the RoHS legal regulations. Traces of dangerous materials may be found in the electronic components, but not in harmful quantities.

## 14. Addendum

### 14.1. Related documents

- Datasheet epc502 , ESPROS Photonics Corp.
- BeagleBone Hardware Specs and Material, BeagleBone Black wiki
- BeagleBone Black System Reference Manual, BeagleBoard.org
- BeagleBone Black, Document No. 450-5500-001 (Schematics), BeagleBoard.org

### 14.2. Links

[www.espros.com](http://www.espros.com)

[www.beagleboard.org](http://www.beagleboard.org)

[www.opencv.org](http://www.opencv.org) - OpenCV (OpenSource Computer Vision)

### 14.3. Licenses

We appreciate the use of the following open source or free software in our tools and respect the large amount of work the owners have done:

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